Study Guides on Computer Networks and Distributed Systems

Clock synchronization and NTP

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Questionnaire

1. The Network Time Protocol (NTP) can be used to synchronize computer clocks. Explain why, even with this service, no bound is given for the resulting time difference between two clocks even right after synchronization.

Computing the offset necessary to add to the requester clock (C_{Req}) which needs to be set to the responder clock (C_{Resp}) time entails determining $Delay_{Return}$ or the average of the return path delay over time. The approximation to $Delay_{Return}$ that we can compute is just $\frac{Rtt}{2}$, which, in reality can depart a lot from the actual $Delay_{Return}$ depending on the degree of asymmetry between the forward and the return paths and their respective delays, so the accuracy of this approximation can introduce a substantial error in the clock.

Perfect synchronization would entail zero-Rtt which is impossible to achieve.

2. What transport does NTP use?

NTP is documented in RFC 5905. The transport used by NTP is UDP

3. When synchronizing computer clocks, can a clock be set back? Explain what has to be done in order for a clock to acquire the same real time as another clock.

Computer clocks, in general, must not be brought back, since that might cause the repetition of certain actions configured by system administrators. The correct action to take upon a clock that must be brought behind consists in reducing its speed so that in a certain period of real time it will be in sync with a remote clock (One that, for some reason, has a good reference time). By decelerating the clock, it will continue generating a sequence of growing time values, though with a reduced accuracy. This so-called *clock monotonicity* will avoid the foregoing undesirable effects altogether. POSIX function adjtime() will accelerate or decelerate the clock to gain or lose some time monotonically.

4. Solve the synchronization example included in the lecture slides

The present example aims to illustrate the synchronization process of two hosts A and B. Host A is the time sync requester and B is the time sync responder. The requester host executes a *naïve* form of Cristian's algorithm in which it performs ten time requests to host B so it can calculate the average Rtt. The relevant timestamps are recorded in the spreadsheet below. The cells in green background represent the problem data that we are given and the gray-blue cells represent the

calculations that we have to do in order to obtain the desired final result: the new time computer A must be set to so it be in sync with B's clock.

Assume min (ms) =					
	Timestamps				
Request no.	Receive	Transmit	Rtt ms	Tresp time (ms)	RttN (ms
1	1:20:32.150	1:20:32.154	31	4	27
2	1:20:34.040	1:20:34.044	29	4	25
3	1:20:37.510	1:20:37.514	28	4	24
4	1:20:40.320	1:20:40.324	29	4	25
5	1:20:44.750	1:20:44.754	28	4	24
6	1:20:49.020	1:20:49.024	30	4	26
7	1:20:55.270	1:20:55.274	29	4	25
8	1:20:58.650	1:20:58.654	30	4	26
9	1:21:02.340	1:21:02.344	31	4	27
10	1:21:08.900	1:21:08.904	31	4	27
		avg(Rtt)	29,6	avg(RttN)	25,6
		avg(Rtt/2)	14,8	avg(RttN/2)	12,8
Max Abs Error (Delay fwd)	2,8				
Max Abs Error (Delay bkwd)	4,8				
Time set =	Transmit[10] + Avg RttN/2 =	1:21:08.904 + 12,8 ms =	1:21:08.9168		

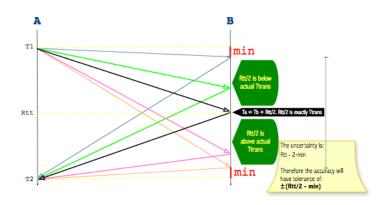
5. Does TCP offer some facility to allow a transmitter to compute the *network Rtt* (Rtt_N) of a connection, *i.e.*, the Rtt that doesn't include the IRQ time (T_{RESP}) consumed by the destination host servicing the request received from the client.

TCP's timestamps can only be used to calculate the overall Rtt, which includes T_{RESP}.

6. Describe the kind of operations caused by the reception of a layer-2 frame. Specifically we wish to obtain a perspective about what happens right after the microprocessor deals with the hardware interrupt which initially reports the full deserialization of a new frame.

This exercise consists of having you review the lab practices of Computer Networks.

- 7. Explain the basic principles underlying the Christian's synchronization algorithm
- 8. Clock synchronization over the internet suffers from a lack of precision, can you explain the cause?
- 9. Tell several ways to have a host synchronized with a UTC source over the Internet
- 10. What is *clock drift?* What is its basic cause?
- 11. Give an explanation of the following diagram:



- 12. Study the solved exercise about Clock Synchro in paloalto.unileon.es/ds
- 13. Solve exercises **14.1 14.5** from Dollimore/Kindberg/Coulouris/etc (You can access the problem statements on the last page of the Physical Clocks ppt lecture presentation)

MORE EXERCISES ON NEXT PAGES

14. Solved exercise about conversion from the h:m:s time format to seconds and microseconds:

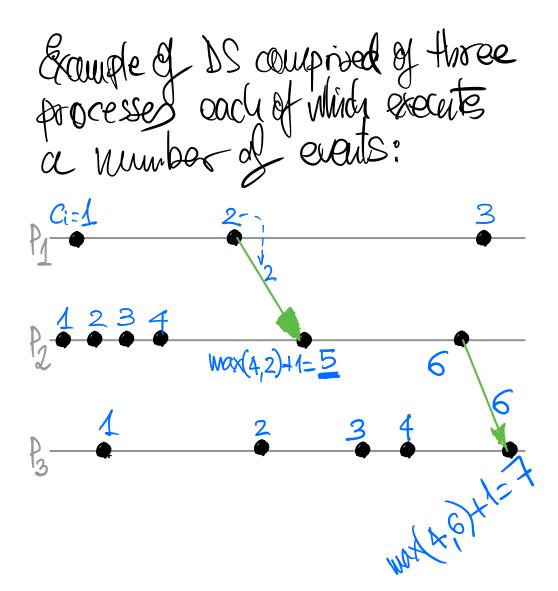
4

1: 10: 55, 282 $\frac{-1:00:55,287}{\emptyset:10:00,095} \rightarrow \text{Result is} - \emptyset:10:00,095 \text{ sec.}$ The actual argument seril on to adjtime() must be expressed as seconds and us (mice seconds), in the present case we have: $-\phi: \Lambda p: DD, pq5 sec = -(\phi \times 60 \times 60 + 10 \times 60 + 00 + 0, 0q5000)$ seconds MS mm The adjtime() function gradually adjusts the system clock (as returned by gettimeofday(2)). The amount of time by which the clock is to be adjusted its specified in the structure pointed by delta. This structure has the following form: struct timeval {
 time_t tv_sec;
 suseconds_t tv_usec;
} /* seconds */ /* microseconds */ }; If the adjustment in *delta* is positive, then the system clock is speeded up by some small percentage (i.e., by adding a small amount of time to the clock value in each second) until the adjustment has been completed. If the adjustment in *delta* is negative, then the clock is slowed down in a similar fashion.

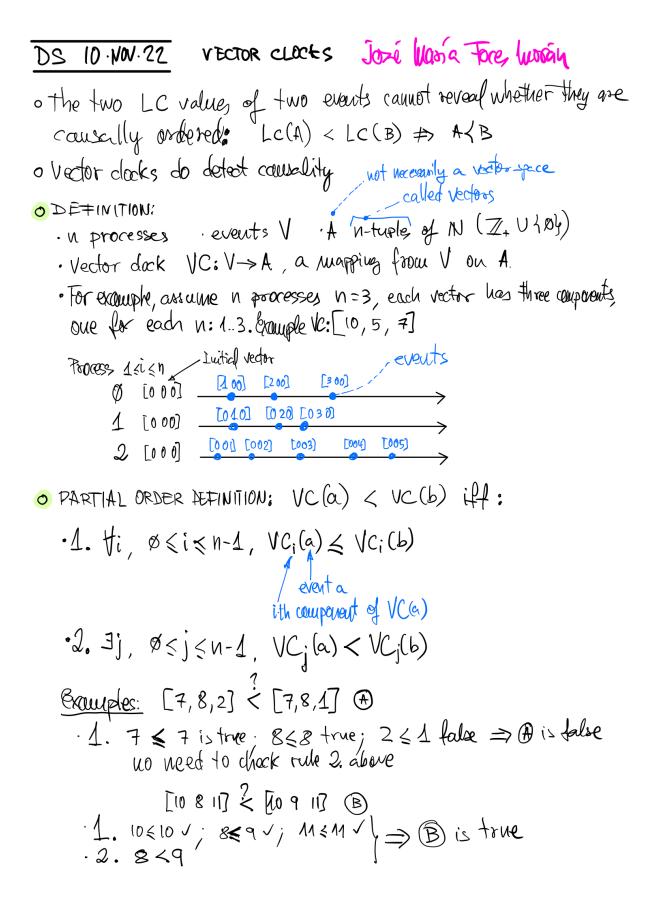
NOTES ABOUT LOGICAL CLOCKS (On next page)

LAMPORT'S CLOCKS (Scalar Anial clocks) DS 29th OCT 2022 o LC = Logical clock • Time is the set N represented by varable G • Civastille reparts le LC of process Pi • events happen in processes (e; e; ...) e; -> e; : The "->" relation means "happened before". The timestorup of ei is smaller than the timestamp of e: • In ligital clocks this property must be true: if $e_i \rightarrow e_j$, then $C(e_i) < ((e_j)$ (construct, monotanicity property) • event e:: - Jeug messcope - Receive Message -Intervol

(Producates 1) Before executive event e: $C_i = C_i + \phi (d > \emptyset, typically 1)$ timestamp of process Pi C:= Max(Ci, Cusz) Receiver Got sender bliver message internal sec PHE 234 processes in DS



NOTES ON VECTOR CLOCKS ON NEXT PAGE



O IMPLEMENTATION OF VEGOR CLOCKS ·We seek a (b >> VC(a) < VC(b) if a(b ⇒ VC(a) < VC(b) and if VC(a) < VC(b) ⇒ a
b if a and b are causally ordered then the VC(a) < VC(b) and if VC(a) < VC(b) ⇒ a
the vC(a) < VC(b) we can claim that they are could by ordered • In processes, ØSiSN-1 VC[0]=Ø · Local, interval events: within a specific process. Example: 2 [000] [001] [002] [003] [004] [005] $VC_i[i] = VC_i[i] + 1/$ [0,03]; $VC_2[2] + 1 = 3 + 1 = 4 : [0,04]$ i=2 · Send events: Diggyback the arrest veter (*) i = 1 [000] <u>[040]</u> [020 [030] **★**=\[0 20] (*****) $i = 2 [000] \xrightarrow{[001] [002]}$ • Receive avents: Create a new event and compute its VC by using-T and the current VC of the receiving process VCr VCr = [002] Since i = 2 we fetch comparent 2 which volue is 2 component \$ 1 2 VCr[r] = VCr[r] +1 in This case VC2[2] = VC[2]+1 = 2+1=3 vew VC2[2]
 (2) Vr: ØSrSn-1 :: VC, Ei] = max (Tr, VC, Ei]) in This case:

$$\begin{bmatrix} 0 & 2 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 3 \end{bmatrix}$$

 $\max(0, \emptyset) = \emptyset$
 $\max(2, \emptyset) = 2$
 $\max(0, 3) = 3$
 $\max(0, 3) = 3$

· EXAMPLE AND QUESTIONS

